This test, relative to Flight Test 1, I increased the weight of the roll pitch yaw rates in order to increase damping. It did not appear to work. However, I notice that motors 2 and 4 are fighting again. It may be worthwhile to revisit the motor characterization data and see if there is a significant imbalance there. For the moment, I’ll try a bigger weight on the controls to try to reduce the aggressiveness of the response, because it appears to be controller driven.